

Self-learning Systems for Cyber Security¹

Kim Hammar & Rolf Stadler

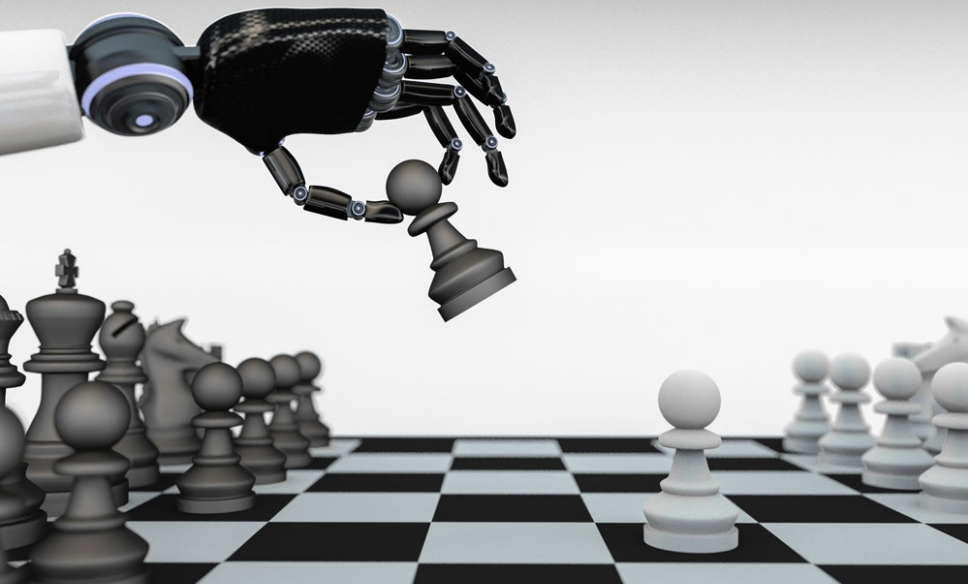
kimham@kth.se & stadler@kth.se

Division of Network and Systems Engineering
KTH Royal Institute of Technology

October 15, 2020

¹Kim Hammar and Rolf Stadler. "Finding Effective Security Strategies through Reinforcement Learning and Self-Play". In: *International Conference on Network and Service Management (CNSM 2020) (CNSM 2020)*. Izmir, Turkey, Nov. 2020.

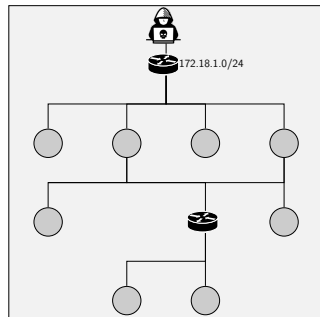
Game Learning Programs



Challenges: Evolving and Automated Attacks

- **Challenges:**

- Evolving & automated attacks
- Complex infrastructures



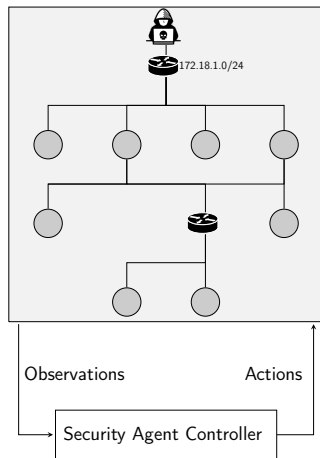
Goal: Automation and Learning

- Challenges

- Evolving & automated attacks
- Complex infrastructures

- **Our Goal:**

- Automate security tasks
- Adapt to changing attack methods



Approach: Game Model & Reinforcement Learning

- **Challenges:**

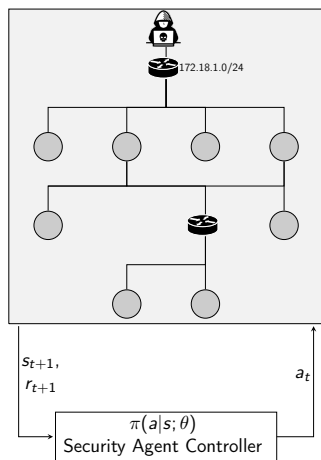
- Evolving & automated attacks
- Complex infrastructures

- **Our Goal:**

- Automate security tasks
- Adapt to changing attack methods

- **Our Approach:**

- Model network as Markov Game
 $\mathcal{M}_G = \langle \mathcal{S}, \mathcal{A}_1, \dots, \mathcal{A}_N, \mathcal{T}, \mathcal{R}_1, \dots, \mathcal{R}_N \rangle$
- Compute policies π for \mathcal{M}_G
- Incorporate π in self-learning systems



- **Game-Learning Programs:**

- TD-Gammon², AlphaGo Zero³, OpenAI Five etc.
- \implies Impressive empirical results of *RL and self-play*

- **Network Security:**

- Automated threat modeling⁴, automated intrusion detection etc.
- \implies Need for *automation* and better security tooling

- **Game Theory:**

- Network Security: A Decision and Game-Theoretic Approach⁵.
- \implies Many security operations involves *strategic decision making*

²Gerald Tesauro. "TD-Gammon, a Self-Teaching Backgammon Program, Achieves Master-Level Play". In: *Neural Comput.* 6.2 (Mar. 1994), 215–219. ISSN: 0899-7667. DOI: 10.1162/neco.1994.6.2.215. URL: <https://doi.org/10.1162/neco.1994.6.2.215>.

³David Silver et al. "Mastering the game of Go without human knowledge". In: *Nature* 550 (Oct. 2017), pp. 354–. URL: <http://dx.doi.org/10.1038/nature24270>.

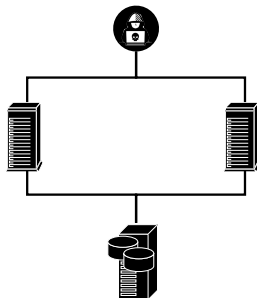
⁴Pontus Johnson, Robert Lagerström, and Mathias Ekstedt. "A Meta Language for Threat Modeling and Attack Simulations". In: *Proceedings of the 13th International Conference on Availability, Reliability and Security. ARES 2018*. Hamburg, Germany: Association for Computing Machinery, 2018. ISBN: 9781450364485. DOI: 10.1145/3230833.3232799. URL: <https://doi.org/10.1145/3230833.3232799>.

⁵Tansu Alpcan and Tamer Basar. *Network Security: A Decision and Game-Theoretic Approach*. 1st. USA: Cambridge University Press, 2010. ISBN: 0521119324.

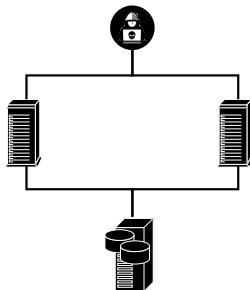
- Use Case
- Markov Game Model for Intrusion Prevention
- Reinforcement Learning Problem
- Method
- Results
- Conclusions

Use Case: Intrusion Prevention

- A **Defender** owns a network infrastructure
 - Consists of connected components
 - Components run network services
 - Defends by monitoring and patching
- An **Attacker** seeks to intrude on the infrastructure
 - Has a partial view of the infrastructure
 - Wants to compromise a specific component
 - Attacks by reconnaissance and exploitation

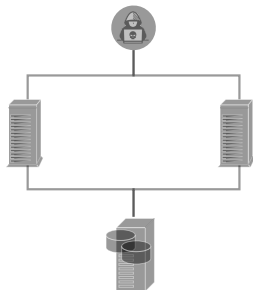


(1) Network Infrastructure

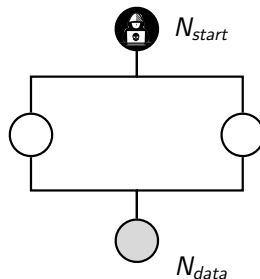


Markov Game Model for Intrusion Prevention

(1) Network Infrastructure

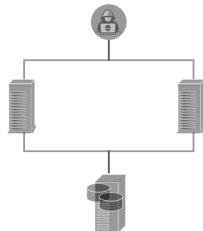


(2) Graph $\mathcal{G} = \langle \mathcal{N}, \mathcal{E} \rangle$

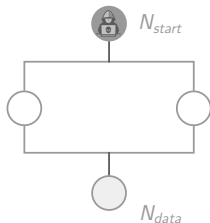


Markov Game Model for Intrusion Prevention

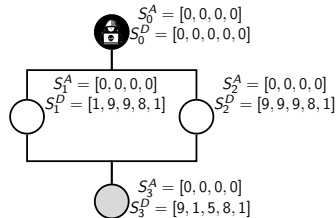
(1) Network Infrastructure



(2) Graph $\mathcal{G} = \langle \mathcal{N}, \mathcal{E} \rangle$

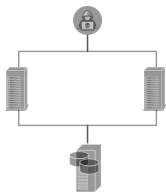


(3) State space $|\mathcal{S}| = (w + 1)^{|\mathcal{N}|} \cdot m \cdot (m+1)$

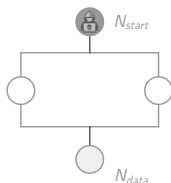


Markov Game Model for Intrusion Prevention

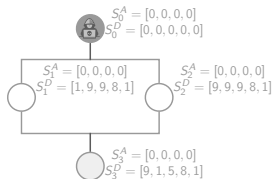
(1) Network Infrastructure



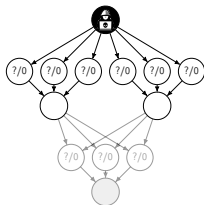
(2) Graph $\mathcal{G} = \langle \mathcal{N}, \mathcal{E} \rangle$



(3) State space $|\mathcal{S}| = (w + 1)^{|\mathcal{N}|} \cdot m \cdot (m + 1)$

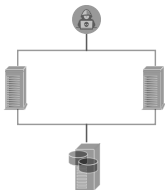


(4) Action space $|\mathcal{A}| = |\mathcal{N}| \cdot (m + 1)$

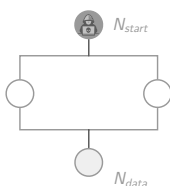


Markov Game Model for Intrusion Prevention

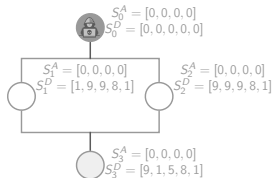
(1) Network Infrastructure



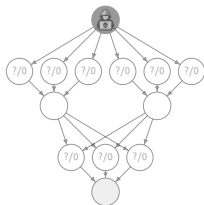
(2) Graph $\mathcal{G} = \langle \mathcal{N}, \mathcal{E} \rangle$



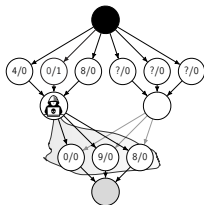
(3) State space $|\mathcal{S}| = (w + 1)^{|\mathcal{N}|} \cdot m \cdot (m + 1)$



(4) Action space $|\mathcal{A}| = |\mathcal{N}| \cdot (m + 1)$

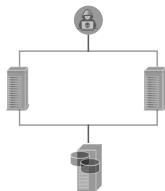


(5) Game Dynamics $\mathcal{T}, \mathcal{R}_1, \mathcal{R}_2, \rho_0$

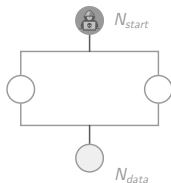


Markov Game Model for Intrusion Prevention

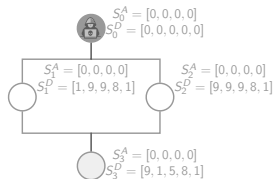
(1) Network Infrastructure



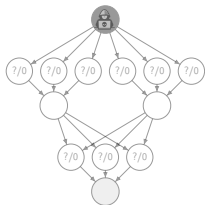
(2) Graph $\mathcal{G} = \langle \mathcal{N}, \mathcal{E} \rangle$



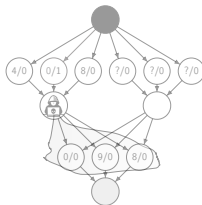
(3) State space $|\mathcal{S}| = (w + 1)^{|\mathcal{N}|} \cdot m \cdot (m+1)$



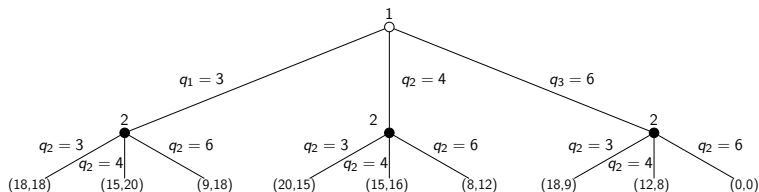
(4) Action space $|\mathcal{A}| = |\mathcal{N}| \cdot (m + 1)$



(5) Game Dynamics $\mathcal{T}, \mathcal{R}_1, \mathcal{R}_2, \rho_0$



- Markov game
 - Zero-sum
 - 2 players
 - Partially observed
 - Stochastic elements
 - Round-based
- $\mathcal{M}_G = \langle \mathcal{S}, \mathcal{A}_1, \mathcal{A}_2, \mathcal{T}, \mathcal{R}_1, \mathcal{R}_2, \gamma, \rho_0 \rangle$



● Finding strategies for the Markov game model:

- Evolutionary methods
- Computational game theory
- Self-Play Reinforcement learning
 - Attacker vs Defender
 - Strategies evolve without human intervention

● Motivation for Reinforcement Learning:

- Strong empirical results in related work
- Can adapt to new attack methods and threats
- Can be used for complex domains that are hard to model exactly

The Reinforcement Learning Problem

- **Goal:**

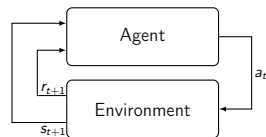
- Approximate $\pi^* = \arg \max_{\pi} \mathbb{E} \left[\sum_{t=0}^T \gamma^t r_{t+1} \right]$

- **Learning Algorithm:**

- Represent π by π_{θ}
- Define objective $J(\theta) = \mathbb{E}_{o \sim \rho^{\pi_{\theta}}, a \sim \pi_{\theta}} [R]$
- Maximize $J(\theta)$ by stochastic gradient ascent with gradient $\nabla_{\theta} J(\theta) = \mathbb{E}_{o \sim \rho^{\pi_{\theta}}, a \sim \pi_{\theta}} [\nabla_{\theta} \log \pi_{\theta}(a|o) A^{\pi_{\theta}}(o, a)]$

- **Domain-Specific Challenges:**

- Partial observability: captured in the model
- Large state space $|\mathcal{S}| = (w + 1)^{|\mathcal{N}| \cdot m \cdot (m+1)}$
- Large action space $|\mathcal{A}| = |\mathcal{N}| \cdot (m + 1)$
- Non-stationary Environment due to presence of adversary



The Reinforcement Learning Problem

- Goal:

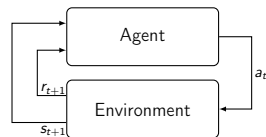
- Approximate $\pi^* = \arg \max_{\pi} \mathbb{E} \left[\sum_{t=0}^T \gamma^t r_{t+1} \right]$

- Learning Algorithm:

- Represent π by π_{θ}
- Define objective $J(\theta) = \mathbb{E}_{o \sim \rho^{\pi_{\theta}}, a \sim \pi_{\theta}} [R]$
- Maximize $J(\theta)$ by stochastic gradient ascent with gradient $\nabla_{\theta} J(\theta) = \mathbb{E}_{o \sim \rho^{\pi_{\theta}}, a \sim \pi_{\theta}} [\nabla_{\theta} \log \pi_{\theta}(a|o) A^{\pi_{\theta}}(o, a)]$

- Domain-Specific Challenges:

- Partial observability: captured in the model
- Large state space $|\mathcal{S}| = (w + 1)^{|\mathcal{N}| \cdot m \cdot (m+1)}$
- Large action space $|\mathcal{A}| = |\mathcal{N}| \cdot (m + 1)$
- Non-stationary Environment due to presence of adversary



The Reinforcement Learning Problem

- Goal:

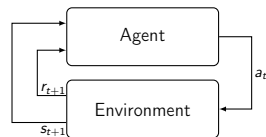
- Approximate $\pi^* = \arg \max_{\pi} \mathbb{E} \left[\sum_{t=0}^T \gamma^t r_{t+1} \right]$

- Learning Algorithm:

- Represent π by π_{θ}
- Define objective $J(\theta) = \mathbb{E}_{o \sim \rho^{\pi_{\theta}}, a \sim \pi_{\theta}} [R]$
- Maximize $J(\theta)$ by stochastic gradient ascent with gradient $\nabla_{\theta} J(\theta) = \mathbb{E}_{o \sim \rho^{\pi_{\theta}}, a \sim \pi_{\theta}} [\nabla_{\theta} \log \pi_{\theta}(a|o) A^{\pi_{\theta}}(o, a)]$

- Domain-Specific Challenges:

- Partial observability: captured in the model
- Large state space $|\mathcal{S}| = (w + 1)^{|\mathcal{N}| \cdot m \cdot (m+1)}$
- Large action space $|\mathcal{A}| = |\mathcal{N}| \cdot (m + 1)$
- Non-stationary Environment due to presence of adversary



Our Reinforcement Learning Method

- **Policy Gradient & Function Approximation**

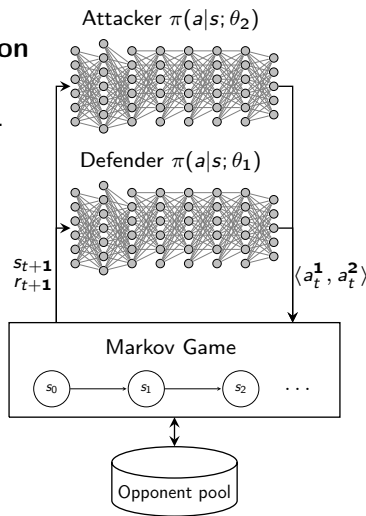
- To deal with large state space \mathcal{S}
- π_θ parameterized by weights $\theta \in \mathbb{R}^d$ of NN.
- PPO & REINFORCE (stochastic π)

- **Auto-Regressive Policy Representation**

- To deal with large action space \mathcal{A}
- To minimize interference
- $\pi(a, n|o) = \pi(a|n, o) \cdot \pi(n|o)$

- **Opponent Pool**

- To avoid overfitting
- Want agent to learn a general strategy



Our Reinforcement Learning Method

- **Policy Gradient & Function Approximation**

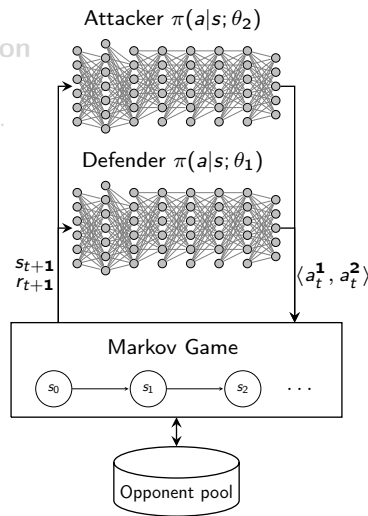
- To deal with large state space \mathcal{S}
- π_θ parameterized by weights $\theta \in \mathbb{R}^d$ of NN.
- PPO & REINFORCE (stochastic π)

- **Auto-Regressive Policy Representation**

- To deal with large action space \mathcal{A}
- To minimize interference
- $\pi(a, n|o) = \pi(a|n, o) \cdot \pi(n|o)$

- **Opponent Pool**

- To avoid overfitting
- Want agent to learn a general strategy



Our Reinforcement Learning Method

- Policy Gradient & Function Approximation

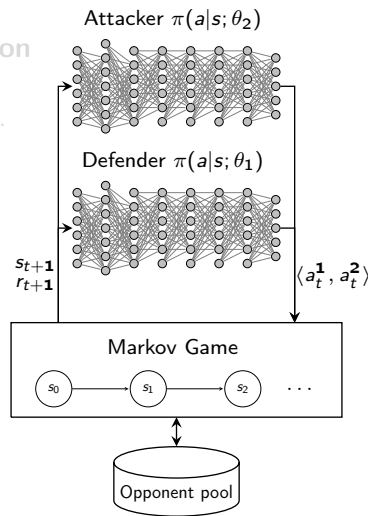
- To deal with large state space \mathcal{S}
- π_θ parameterized by weights $\theta \in \mathbb{R}^d$ of NN.
- PPO & REINFORCE (stochastic π)

- Auto-Regressive Policy Representation

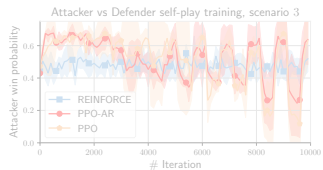
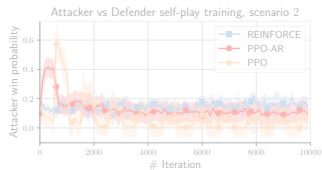
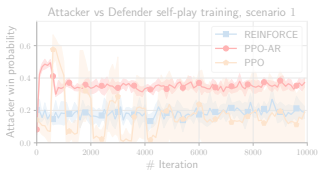
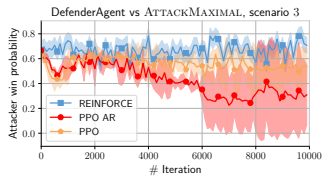
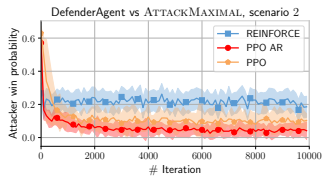
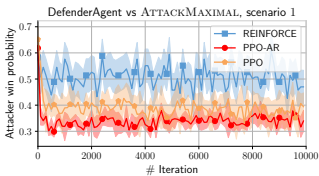
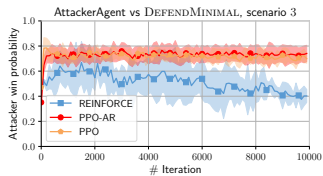
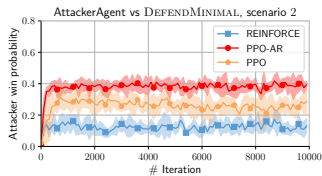
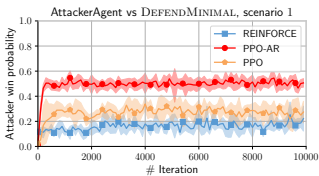
- To deal with large action space \mathcal{A}
- To minimize interference
- $\pi(a, n|o) = \pi(a|n, o) \cdot \pi(n|o)$

- Opponent Pool

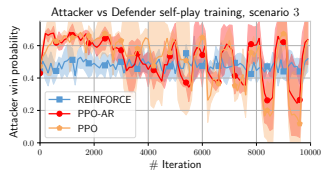
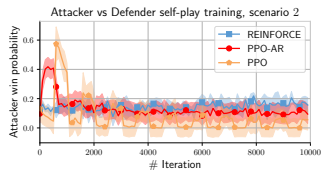
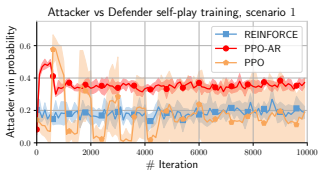
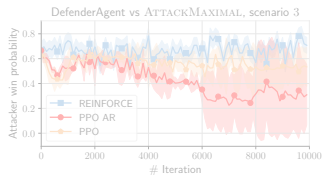
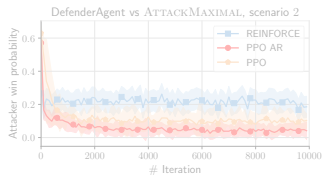
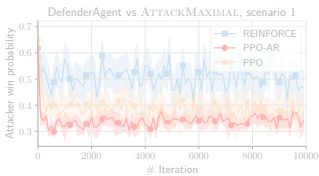
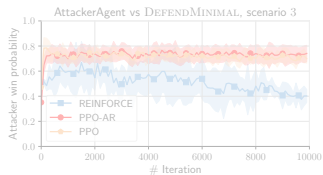
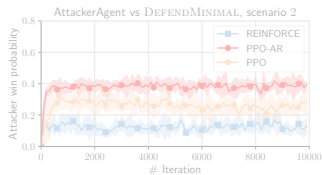
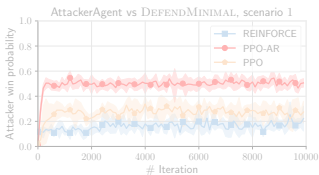
- To avoid overfitting
- Want agent to learn a general strategy



Experimentation: Learning from Zero Knowledge



Experimentation: Learning from Zero Knowledge



• Conclusions:

- We have proposed a *Method* to automatically find security strategies
- \implies Model as Markov game & evolve strategies using self-play reinforcement learning
- Addressed domain-specific challenges with Auto-regressive policy, opponent pool, and function approximation.
- Challenges of applied reinforcement learning
 - Stable convergence remains a challenge
 - Sample-efficiency is a problem
 - Generalization is a challenge

• Current & Future Work:

- Study techniques for mitigation of identified RL challenges
- Learn security strategies by interaction with a cyber range

Thank you

- All code for reproducing the results is open source:
<https://github.com/Limmen/gym-idsgame>